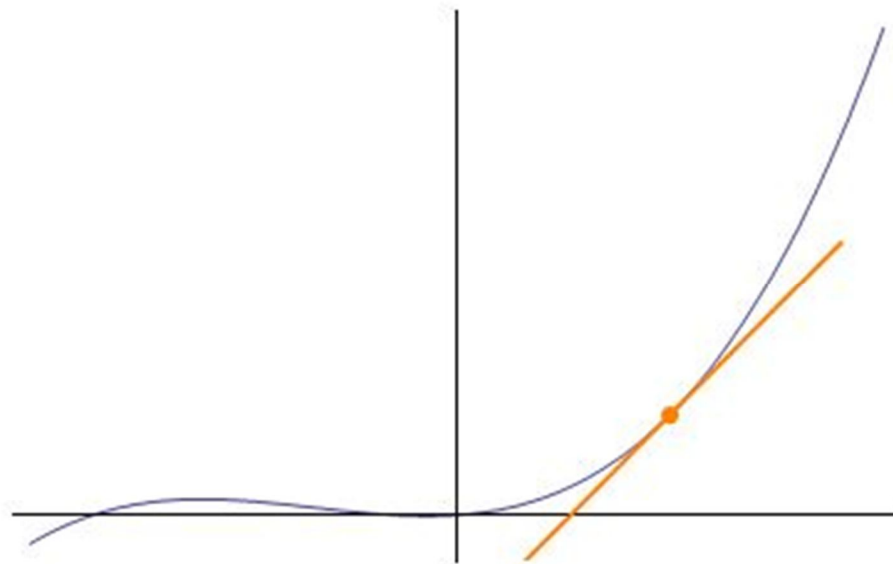


CALCULUS

Chapter 3 –Applications of the Derivative

(Material adapted from Chapter 3 of your text)



$A\infty\Omega$
MATH@TD

Chapter 3 – Applications of the Derivative

Contents with suggested problems from the Nelson Textbook (Chapter 3)

3.1 Higher Order Derivatives: Velocity and Acceleration – Pg 49 – 51

Pg. 127 - 129 #2 – 5, 8, 10, 12 – 16, Read Ex's 2 and 4

3.2 Extreme Values – Pg 52 -54

Pg. 135 – 138 #1 – 4, 6 – 13

3.3 Optimization – Pg 55 – 57

Pg. 145 #4 - 8

3.3b More Optimization Examples – Pg. 58 – 60

Pg. 151 – 154 #3 – 7, 9 – 11, 14, 15

3.1 Higher Order Derivatives: Velocity and Acceleration

Higher Order Derivatives

Recall that given some function $f(x)$ we can find the derivative $f'(x)$ which is itself a function. Thus, we should be able to find the “**derivative of the derivative**”. This is the essence of **higher order derivatives**.

Example 3.1.1

Consider the function:

$$f(x) = 3x^4 - 2x^2 + 1$$

Question

Given a polynomial function of degree n , what is the maximum number of derivatives that can be calculated?

Position, Velocity and Acceleration

We will consider the motion of a particle in a straight line for our considerations of velocity and acceleration. One thing will be necessary. **We must define a positive direction of motion**, and interpret our results in light of that definition.

Example 3.1.2

Given that an object is moving in a straight line, and that the object's position is defined/modelled by

$$s(t) = t^3 - 6t^2, \quad t \geq 0$$

Determine:

- a) $v(t)$
- b) $a(t)$
- c) in what direction the object is moving at $t = 1$ sec, $t = 3$ sec, $t = 5$ seconds.
Assume that moving to the right is motion in the positive direction.
- d) the object's acceleration at the same times as in part c).
- e) when the object is at rest.
- f) when the acceleration is zero
- g) draw a **position diagram** describing the motion of the object.

Class/Homework for Section 3.1

Pg. 127 - 129 #2 – 5, 8, 10, 12 – 16, Read Ex's 2 and 4