

VECTORS

Chapter 7 –Applications of Vectors

(Material adapted from Chapter 7 of your text)

$A\infty\Omega$
MATH@TD

Chapter 7 – Applications of Vectors

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Take Check
y 8.85

15. The vectors \vec{a} and \vec{b} span \mathbb{R}^2 . What values of m and n will make the following statement true: $(m - 2)\vec{a} = (n + 3)\vec{b}$? Explain your reasoning.

$$\text{Since } \text{span}\{\vec{a}, \vec{b}\} = \mathbb{R}^2$$

$$\Rightarrow \nexists \text{ scalar } k \neq 0 \text{ st. } \vec{a} = k\vec{b} \quad (\text{ie } \vec{a} \text{ \& } \vec{b} \text{ are not collinear})$$

$$\Rightarrow \text{ in } (m-2)\vec{a} = (n+3)\vec{b}$$

$$m-2 = 0 \quad \text{and} \quad n+3 = 0$$

$$\Rightarrow m = 2 \quad | \quad n = -3$$

7.1 & 7.2 Vectors as Force and Acceleration

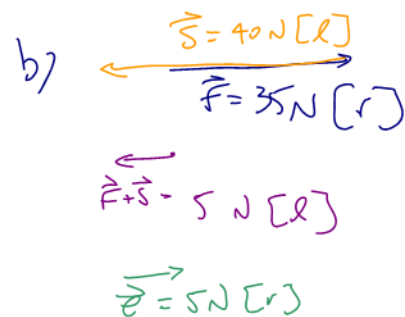
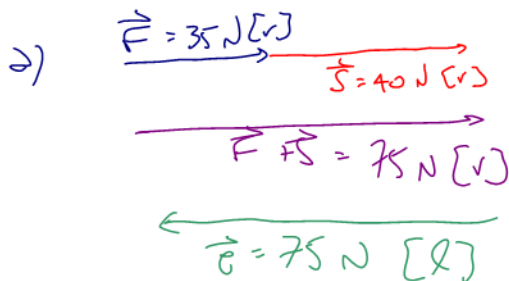
Both **force** and **velocity** are 'real world' qualities which have **magnitude** (size) and **direction**. Thus we can use the mathematics of vectors to solve "real world problems".

Example 7.1.1

A box is being pushed along the floor by Fred and Sally. Fred pushes the box with a force of 35 N [right]. Sally pushes with a force of:

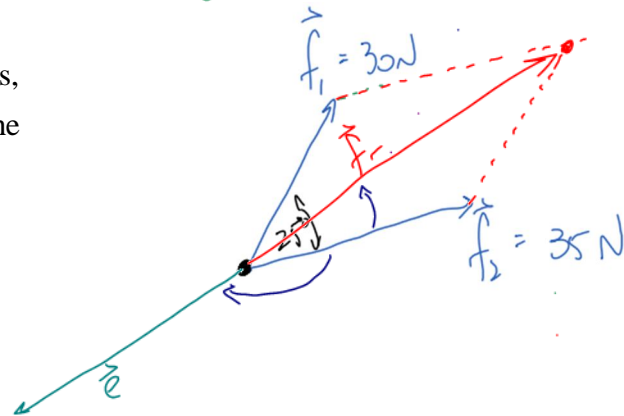
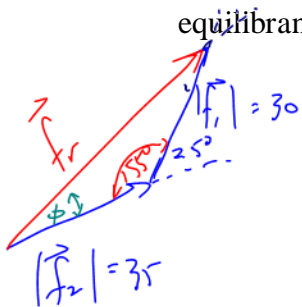
- a) 40 N [right] b) 40 N [left]

For a) and b) determine i) the resultant force \vec{f}_r and ii) the equilibrant of the system \vec{e} .



Example 7.1.2

Given the diagram of a system of forces, determine the resultant force \vec{f}_r , and the equilibrant \vec{e} .



$$|\vec{f}_r| = \sqrt{35^2 + 30^2 - 2(35)(30)\cos(155)}$$

$$= 63.47\text{ N}$$

$$\frac{\sin \phi}{30} = \frac{\sin 155}{63.47}$$

$$\phi = \sin^{-1}\left(\frac{(30)(\sin(155))}{63.47}\right)$$

$$= 11.5^\circ$$

we still need direction

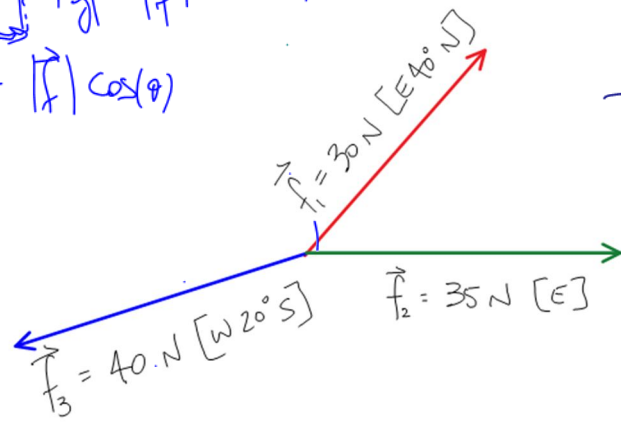
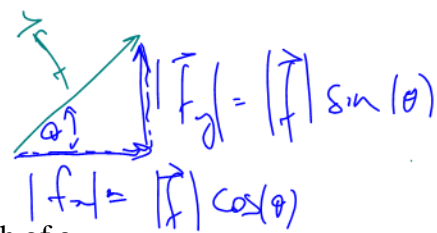
$$\therefore \vec{f}_r = 63.47\text{ N}, 11.5^\circ \text{ from } \vec{f}_2 \quad \therefore \vec{e} = 63.47\text{ N } 168.5^\circ \text{ from } \vec{f}_2$$

Example 7.1.3

Consider the following sketch of a system of forces:

Determine \vec{f}_r .

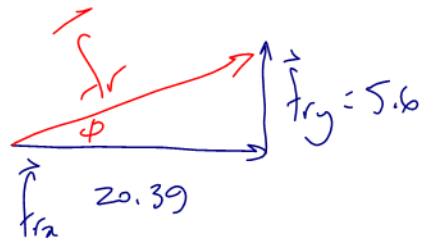
We will separate all forces
into their **rectangular components**
 \vec{f}_x, \vec{f}_y (using a cheat)



VECTOR	x component	y component
$\vec{F}_1 = 30 \text{ N } [E40^\circ N]$	$\vec{F}_{1x} = 30 \cos(40) [E]$ $= 22.98 [E]$	$\vec{F}_{1y} = 30 \sin(40) [N]$ $= 19.28 [N]$
$\vec{F}_2 = 35 \text{ N } [E]$	$\vec{F}_{2x} = 35 [E]$	$\vec{F}_{2y} = \vec{0}$
$\vec{F}_3 = 40 \text{ N } [W20^\circ S]$	$\vec{F}_{3x} = 40 \cos(20) [W]$ $= 37.59 [W]$	$\vec{F}_{3y} = 40 \sin(20) [S]$ $= 13.68 [S]$
$\vec{F}_r = ?$	$\vec{F}_{rx} = 22.98 + 35 - 37.59$ $= 20.39 \text{ N } [E]$	$\vec{F}_{ry} = 19.28 - 13.68 [N]$ $= 5.6 \text{ N } [N]$

Now we need \vec{F}_r

The "resulting" forces



magnitude

$$\begin{aligned} |\vec{f}_r| &= \sqrt{(|\vec{f}_{rx}|)^2 + (|\vec{f}_{ry}|)^2} \\ &= \sqrt{(20.39)^2 + (5.6)^2} \\ &= 21.14 \text{ N} \end{aligned}$$

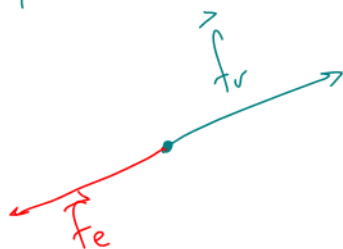
direction

$$\begin{aligned} \tan \phi &= \frac{5.6}{20.39} \\ \Rightarrow \phi &= \tan^{-1} \left(\frac{5.6}{20.39} \right) \\ &= 15.4^\circ \end{aligned}$$

$$\therefore \vec{f}_r = 21.14 \text{ N } [15.4^\circ \text{ N}]$$

Another look at Equilibrium

Recall that a system of vectors in ^{equilibrium} can be represented by two "opposite" vectors:

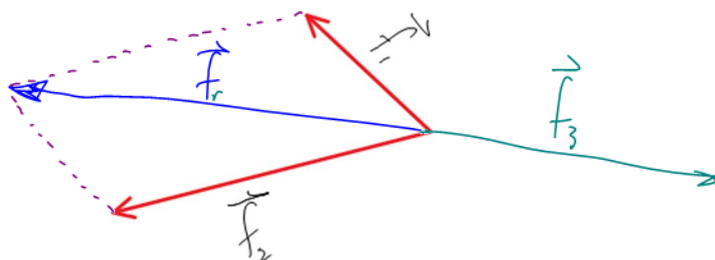


$$\vec{f}_e = -\vec{f}_r$$

$$\Rightarrow \vec{f}_e + \vec{f}_r = \vec{0}$$

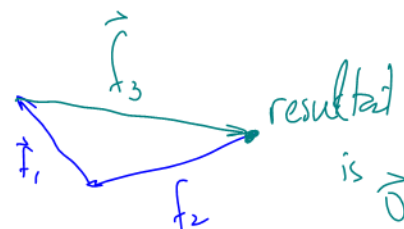
Example 7.1.4

Given that three forces \vec{f}_1 , \vec{f}_2 , and \vec{f}_3 are in equilibrium, with \vec{f}_1 and \vec{f}_2 as shown, determine \vec{f}_3 (as a sketch).



Note: A system in equilibrium has "no resultant"

$$\text{ie } \vec{f}_1 + \vec{f}_2 + \vec{f}_3 = \vec{0}$$



Class/Homework for Section 7.1

*Pg. 362 – 364 #2 – 6, 8, 9, 15,
Pg. 369 – 370 #2 – 4, 6, 7, 9, 11*